

## Main Features

- NEW Control panel with Real time clock. Optional Bluetooth communication.
- Available as robust and certified IP54 metal construction or IP20/21 version.
- All drive sizes are delivered with built-in Category C3 EMC-filter as standard. C3 requirements are fulfilled with 80 m motor cable (IP2Y= 25m).
- Soft starts minimize start currents and linear stops prevent water hammer.
- One Emotron FDU can control up to seven pumps/fans without external control systems.
- Energy saving function pauses the motor when it is not required to run to maintain pressure.
- Efficiency is increased by setting the pump to run at full speed at certain intervals to rinse out sludge.
- Temp/Speed controlled fans assures less noise, a more even drive temperature and higher efficiency.
- Load monitor function included as standard.
- Detachable multi-language control panel included as standard. Following languages are supported in the control panel:
- English, Swedish, Dutch, German, French, Spanish, Russian, Italian, Czech, Turkish and Polish.
- Operation parameters can be set in your process units, for example m3/min. and bar.
- Removable control panel with own memory means it is easy to transfer or copy settings.
- UL (UL 840) approved version available (not IP2Y).
- Marine (DNV-GL & BV) approved version available (not IP2Y, IP2x).
- Liquid cooled version available for sizes above 90 A



## GENERAL SPECIFICATION

| Component name  | FDU69-002-54   |
|---|--|
| Suitable Motor Capacity   |  |
| Capacity( <i>KW</i> )   | 1.5  |
| Rated Output Current(A)   | 2  |
| Maximum Output Current(A)   | 3.2  |
| Input Voltage Range(V)  | Three-phase 400~ 690V, 50/60Hz   |
| Allowable Voltage Fluctuation                                       | -15%~+10%  |
| Output Voltage range(V)   | Three-phase 0~480V   |
| Mains Frequency (Hz)  | 45 to 65   |
| Output Switching Frequency ( <i>kHz</i> )                           | 3  |
| Input Power Factor (%)  | 0.95   |
| Environmental conditions  |  |
| Nominal ambient temperature   | 0°C - 40°C (32°F- 104°F)   |
| Atmospheric pressure  | 86–106 kPa ( 12.5 - 15.4 PSI)  |
| Relative humidity   |  |
| according to IEC 60721-3-3  | Class 3K4, 595% and no condensing  |
|   |  |
| Contamination,  | No electrically conductive dust allowed. Cooling air must be clean                             |
| according to IEC 60721-3-3  | and free from corrosive materi-als. Chemical gases, class 3C2                                  |
|   | (coated boards 3C3). Solid particles, class 3S2.   |
| Component name  | VFX48-2K5-54   |
| Vibrations  | According to IEC 60068-2-6, Sinusoidal vibrations:   |
|   | 10 <f<57 (0.00295="" 0.075="" ft)<="" hz,="" mm="" td=""></f<57>                               |
|   | 57 <f<150 (0,035="" 1g="" hz,="" oz)<="" td=""></f<150>  |
|   |  |
| Altitude  | 0–1000 m (0 - 3280 ft) with derating 1%/100 m (328 ft) of                                      |
|   | rated current  |
| Storage temperature   | $-20 \text{ to } +60 ^{\circ}\text{C} (-4 \text{ to } + 140 ^{\circ}\text{F})$                 |
| Storage atmospheric pressure<br>Storage relative humidity according | 86–106 kPa (12.5 - 15.4 PSI)<br>Class 1K4, max. 95% and no condensing and no formation of ice. |
| to IEC60721-3-1   | Class 1K4, max. 95% and no condensing and no formation of ice.                                 |
|   |  |
| Basic I/O Data  |  |
| Control signal inputs: Analogue (differen                           | ntial), 4 channels   |
| Analogue voltage/current  | 0-±10 V/0-20 mA via switch   |
| Max. input voltage  | +30 V  |
| Input impedance   | 20 kΩ (voltage), 250 Ω (current)   |
| Resolution  | 11 bits + sign   |
| Hardware accuracy   | 0.5% type + 1 ½ LSB fsd  |
| Non-linearity   | 1½ LSB   |
| Digital inputs: 8 channels  |  |
| Input voltage   | High >9 VDC, Low<4 VDC   |
| · · · · · · · · · · · · · · · · · · ·                               |  |
| Max. input voltage  | +30 VDC<br><3.3 VDC: 4.7 kΩ , ≥3.3 VDC: 3.6 kΩ   |

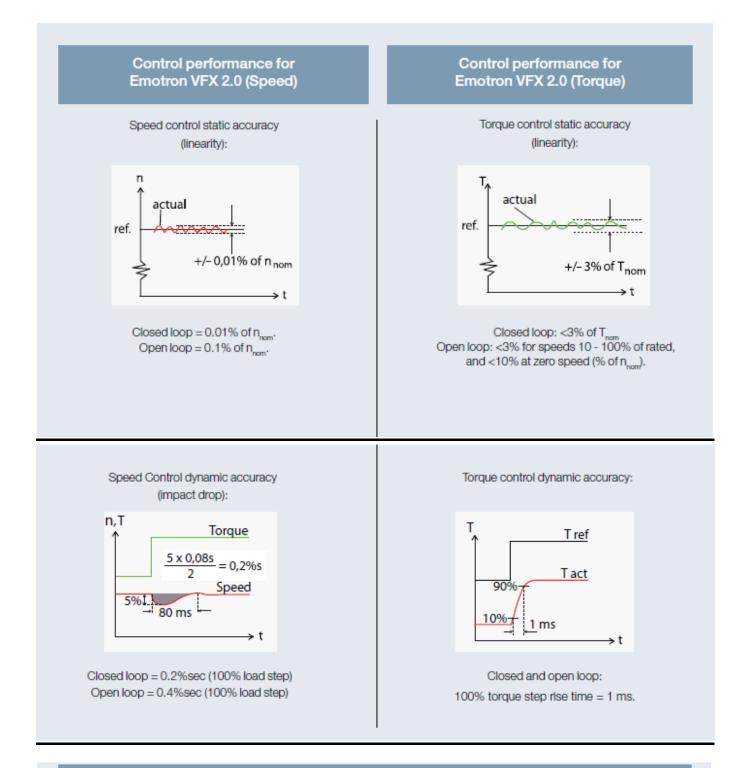
## Product data sheet



| Signal delay                                 | ≤8 ms   |  |
|--|---|--|
| Control signal outputs: Analogue, 2 channels |   |  |
| Output voltage/current                       | 0-10 V/0-20 mA via software setting                                       |  |
| Max. output voltage                          | +15 V @5 mA cont.   |  |
| Short-circuit current (∞)                    | +15 mA (voltage) +140 mA (current)  |  |
| Output impedance                             | $10 \Omega$ (voltage)   |  |
| Resolution                                   | 10 bit  |  |
| Maximum load impedance for current           | 500 Ω   |  |
| Hardware accuracy                            | 1.9% type fsd (voltage), 2.4% type fsd (current)                          |  |
| Offset                                       | 3 LSB   |  |
| Non-linearity                                | 2 LSB   |  |
| Digital outputs: 2 channels                  |   |  |
| Output voltage                               | High>20 VDC @50 mA, >23 VDC open<br>Low<1 VDC @50 mA                      |  |
| Short-circuit current (∞)                    | 100 mA max (together with +24 VDC)  |  |
| Relays, 3pcs                                 |   |  |
| Contacts                                     | 0.1 – 2 A/Umax 250 VAC or 42 VDC  |  |
| Reference voltages                           |   |  |
| +10 VDC                                      | +10 VDC @10 mA short-circuit current +30 mA max                           |  |
| -10 VDC                                      | -10 VDC @10 mA  |  |
| +24 VDC                                      | +24 VDC short-circuit current +100 mA max (together with Digital Outputs) |  |



### PERFORMANCE

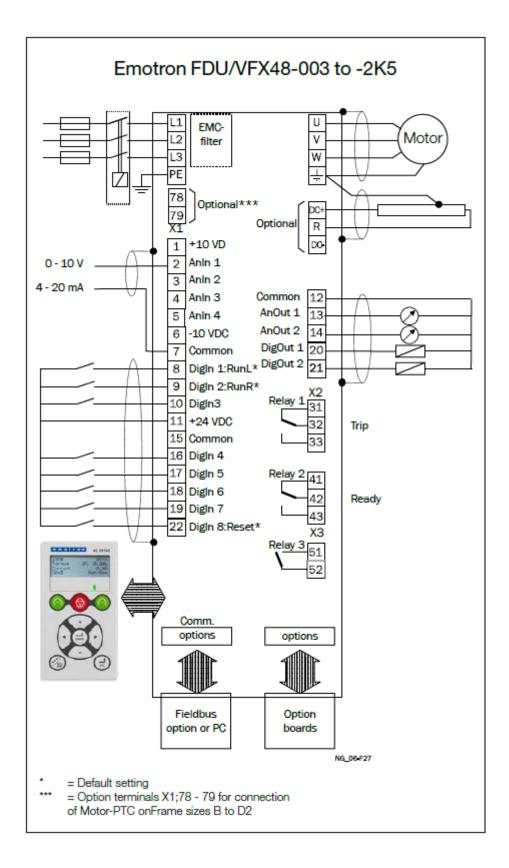


#### Control performance for Emotron FDU 2.0 (V/Hz)

Speed control accuracy = approximately 1% of nnom (slip frequency). Torque accuracy = approximately 5% of Tnom (20 - 100% speed).

# TEC

## GENERAL WIRING DIAGRAM





| X1 | Name:   | Function (Default):    |
|----|---------|------------------------|
| 1  | +10V    | +10 VDC Supply voltage |
| 2  | AnIn 1  | Speed reference        |
| 3  | AnIn 2  | Not Used               |
| 4  | AnIn 3  | Not Used               |
| 5  | AnIn 4  | Not Used               |
| 6  | -10V    | -10VDC Supply voltage  |
| 7  | Common  | Signal ground          |
| 8  | DigIn 1 | RunL                   |
| 9  | DigIn 2 | RunR                   |
| 10 | DigIn 3 | Not Used               |
| 11 | +24VDC  | +24VDC Supply voltage  |
| 12 | Common  | Signal ground          |
| 13 | AnOut 1 | Min speed to max speed |
| 14 | AnOut 2 | 0 to max torque        |
| 15 | Common  | Signal ground          |
| 16 | DigIn 4 | Not Used               |
| 17 | DigIn 5 | Not Used               |
| 18 | DigIn 6 | Not Used               |
| 19 | DigIn 7 | Not Used               |

| X1 | Name:    | Function (Default):   |
|----|----------|---|
| 20 | DigOut 1 | Ready   |
| 21 | DigOut 2 | Brake/No trip   |
| 22 | DigIn 8  | Reset   |
| X2 | Name:    |   |
| 31 | N/C 1    | Relay 1 Output= Trip.   |
| 32 | COM 1    | Active when the AC drive is   |
| 33 | N/O 1    | in a Trip condition. The N/C<br>is opened when the relay is<br>active (valid for all relays).<br>The N/O is closed when the<br>relay is active (valid for all<br>relays). |
| 41 | N/C 2    | Relay 2 Output= Ready.  |
| 42 | COM 2    | Active when the AC drive is   |
| 43 | N/O 2    | ready to start.   |
| X3 | Name:    | Function (Default):   |
| 51 | COM 3    | Relay 3 Output= Not used.   |
| 52 | N/0 3    |   |

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DRIVE DIMENSIONS (Hx Wx D): preliminary 512x 178x 314 (mm).

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