## TEC®

### **Product data sheet Emotron**

### Variable speed drive FDU69-300-IP/ 315KW/ 400-690V

### **Main Features**

- NEW Control panel with Real time clock. Optional Bluetooth communication.
- Available as robust and certified IP54 metal construction or IP20/21 version.
- All drive sizes are delivered with built-in Category C3 EMC-filter as standard. C3 requirements are fulfilled with 80 m motor cable (IP2Y= 25m).
- Soft starts minimize start currents and linear stops prevent water hammer.
- One Emotron FDU can control up to seven pumps/fans without external control systems.
- Energy saving function pauses the motor when it is not required to run to maintain pressure.
- Efficiency is increased by setting the pump to run at full speed at certain intervals to rinse out sludge.
- Temp/Speed controlled fans assures less noise, a more even drive temperature and higher efficiency.
- Load monitor function included as standard.
- Detachable multi-language control panel included as standard. Following languages are supported in the control panel:
- English, Swedish, Dutch, German, French, Spanish, Russian, Italian, Czech, Turkish and Polish.
- Operation parameters can be set in your process units, for example m3/min. and bar.
- Removable control panel with own memory means it is easy to transfer or copy settings.
- UL (UL 840) approved version available (not IP2Y).
- Marine (DNV-GL & BV) approved version available (not IP2Y, IP2x).
- Liquid cooled version available for sizes above 90 A



## **Product data sheet**

## GENERAL SPECIFICATION

| Component name                           | FDU69-300-IP  |
|--|---|
| Suitable Motor Capacity                  | 215   |
| Capacity(KW)                             | 315   |
| Rated Output Current(A)                  | 300   |
| Maximum Output Current(A)                | 360   |
| Input Voltage Range(V)                   | Three-phase 400~ 690V, 50/60Hz  |
| Allowable Voltage Fluctuation            | -15%~ +10%  |
| Output Voltage range(V)                  | Three-phase 0~480V  |
| Mains Frequency (Hz)                     | 45 to 65  |
| Output Switching Frequency (kHz)         | 3   |
| Input Power Factor (%)                   | 0.95  |
| Environmental conditions                 |   |
| Nominal ambient temperature              | 0°C - 40°C (32°F- 104°F)  |
| Atmospheric pressure                     | 86–106 kPa ( 12.5 - 15.4 PSI)   |
| Relative humidity                        |   |
| according to IEC 60721-3-3               | Class 3K4, 595% and no condensing                                       |
|  |   |
| Contamination,                           | No electrically conductive dust allowed. Cooling air must be clean      |
| according to IEC 60721-3-3               | and free from corrosive materi-als. Chemical gases, class 3C2           |
|  | (coated boards 3C3). Solid particles, class 3S2.                        |
| Component name                           | VFX48-2K5-54  |
| Vibrations                               | According to IEC 60068-2-6, Sinusoidal vibrations:                      |
|  | 10 <f<57 (0.00295="" 0.075="" ft)<="" hz,="" mm="" td=""></f<57>        |
|  | 57 <f<150 (0,035="" 1g="" hz,="" oz)<="" td=""></f<150>                 |
| Alice J.                                 | 0. 1000 (0. 2200 ft) th. la t 10/ /100 (220 ft)                         |
| Altitude                                 | 0–1000 m (0 - 3280 ft) with derating 1%/100 m (328 ft) of rated current |
| Storage temperature                      | -20 to +60 °C (-4 to + 140 °F)  |
| Storage atmospheric pressure             | 86–106 kPa (12.5 - 15.4 PSI)  |
| Storage relative humidity according      | Class 1K4, max. 95% and no condensing and no formation of ice.          |
| to IEC60721-3-1                          | Glass Tivi, max. 95% and no condensing and no formation of fee.         |
|  |   |
| Basic I/O Data                           |   |
| Control signal inputs: Analogue (differe | ntial), 4 channels  |
| Analogue voltage/current                 | 0-±10 V/0-20 mA via switch  |
| Max. input voltage                       | +30 V   |
| Input impedance                          | $20 \text{ k}\Omega$ (voltage), 250 Ω (current)                         |
| Resolution                               | 11 bits + sign  |
| Hardware accuracy                        | 0.5% type + 1 ½ LSB fsd   |
| Non-linearity                            | 1½ LSB  |
| Digital inputs: 8 channels               |   |
| Input voltage                            | High >9 VDC, Low<4 VDC  |
| Max. input voltage                       | +30 VDC   |
| Input impedance                          | <3.3 VDC: 4.7 kΩ , ≥3.3 VDC: 3.6 kΩ                                     |



# **Product data sheet**

| Signal delay                                 | ≤8 ms   |  |
|--|---|--|
| Control signal outputs: Analogue, 2 channels |   |  |
| Output voltage/current                       | 0-10 V/0-20 mA via software setting                                       |  |
| Max. output voltage                          | +15 V @5 mA cont.   |  |
| Short-circuit current (∞)                    | +15 mA (voltage) +140 mA (current)  |  |
| Output impedance                             | 10 Ω (voltage)  |  |
| Resolution                                   | 10 bit  |  |
| Maximum load impedance for current           | 500 Ω   |  |
| Hardware accuracy                            | 1.9% type fsd (voltage), 2.4% type fsd (current)                          |  |
| Offset                                       | 3 LSB   |  |
| Non-linearity                                | 2 LSB   |  |
| Digital outputs: 2 channels                  |   |  |
| Output voltage                               | High>20 VDC @50 mA, >23 VDC open  |  |
|  | Low<1 VDC @50 mA  |  |
| Short-circuit current (∞)                    | 100 mA max (together with +24 VDC)  |  |
| Relays, 3pcs                                 |   |  |
| Contacts                                     | 0.1 - 2 A/Umax 250 VAC or 42 VDC  |  |
| Reference voltages                           |   |  |
| +10 VDC                                      | +10 VDC @10 mA short-circuit current +30 mA max                           |  |
| -10 VDC                                      | -10 VDC @10 mA  |  |
| +24 VDC                                      | +24 VDC short-circuit current +100 mA max (together with Digital Outputs) |  |

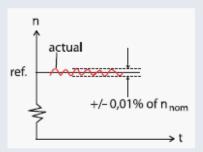




#### **PERFORMANCE**

#### Control performance for Emotron VFX 2.0 (Speed)

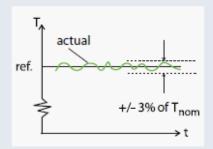
Speed control static accuracy (linearity):



Closed loop = 0.01% of  $n_{nom}$ . Open loop = 0.1% of  $n_{nom}$ .

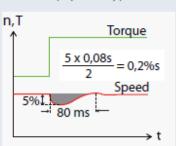
#### Control performance for Emotron VFX 2.0 (Torque)

Torque control static accuracy (linearity):

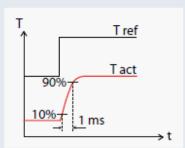


Closed loop: <3% of T<sub>nom</sub>
Open loop: <3% for speeds 10 - 100% of rated, and <10% at zero speed (% of n<sub>nom</sub>).

Speed Control dynamic accuracy (impact drop):



Closed loop = 0.2%sec (100% load step) Open loop = 0.4%sec (100% load step) Torque control dynamic accuracy:



Closed and open loop: 100% torque step rise time = 1 ms.

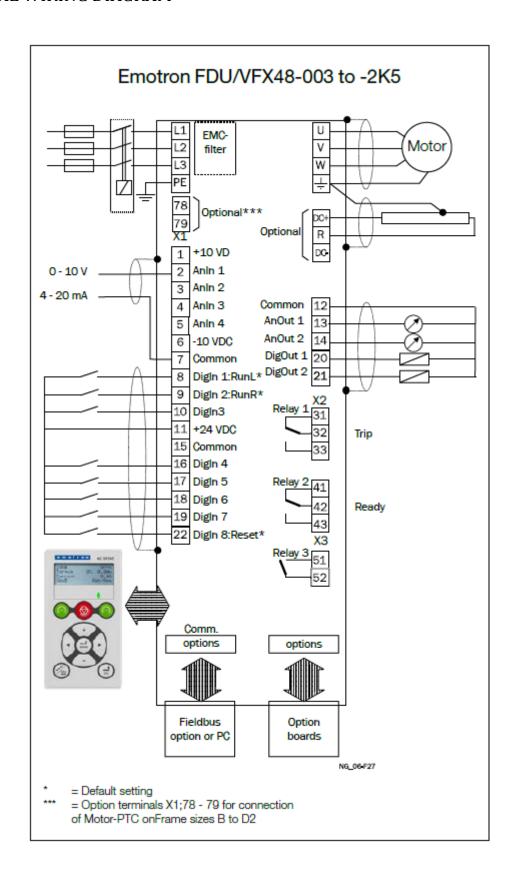
#### Control performance for Emotron FDU 2.0 (V/Hz)

Speed control accuracy = approximately 1% of nnom (slip frequency). Torque accuracy = approximately 5% of Tnom (20 - 100% speed).





#### GENERAL WIRING DIAGRAM







| X1 | Name:   | Function (Default):    |
|----|---------|------------------------|
| 1  | +10V    | +10 VDC Supply voltage |
| 2  | AnIn 1  | Speed reference        |
| 3  | AnIn 2  | Not Used               |
| 4  | AnIn 3  | Not Used               |
| 5  | AnIn 4  | Not Used               |
| 6  | -10V    | -10VDC Supply voltage  |
| 7  | Common  | Signal ground          |
| 8  | DigIn 1 | RunL                   |
| 9  | DigIn 2 | RunR                   |
| 10 | DigIn 3 | Not Used               |
| 11 | +24VDC  | +24VDC Supply voltage  |
| 12 | Common  | Signal ground          |
| 13 | AnOut 1 | Min speed to max speed |
| 14 | AnOut 2 | 0 to max torque        |
| 15 | Common  | Signal ground          |
| 16 | DigIn 4 | Not Used               |
| 17 | DigIn 5 | Not Used               |
| 18 | DigIn 6 | Not Used               |
| 19 | DigIn 7 | Not Used               |

| X1 | Name:    | Function (Default):  |
|----|----------|--|
| 20 | DigOut 1 | Ready  |
| 21 | DigOut 2 | Brake/No trip  |
| 22 | DigIn 8  | Reset  |
| X2 | Name:    |  |
| 31 | N/C 1    | Relay 1 Output= Trip.  |
| 32 | COM 1    | Active when the AC drive is  |
| 33 | N/O 1    | in a Trip condition. The N/C is opened when the relay is active (valid for all relays). The N/O is closed when the relay is active (valid for all relays). |
| 41 | N/C 2    | Relay 2 Output= Ready.   |
| 42 | COM 2    | Active when the AC drive is  |
| 43 | N/0 2    | ready to start.  |
| Х3 | Name:    | Function (Default):  |
| 51 | COM 3    | Relay 3 Output= Not used.  |
| 52 | N/0 3    |  |

### **DRIVE DIMENSIONS**

(Hx Wx D): preliminary 2250x 600x 600 (mm).

