

Main Features

- NEW Control panel with Real time clock. Optional Bluetooth communication.
- Available as robust and certified IP54 metal construction or IP20/21 version.
- All drive sizes are delivered with built-in Category C3 EMC-filter as standard. C3 requirements are fulfilled with 80 m motor cable (IP2Y= 25m).
- Soft starts minimize start currents and linear stops prevent water hammer.
- One Emotron FDU can control up to seven pumps/fans without external control systems.
- Energy saving function pauses the motor when it is not required to run to maintain pressure.
- Efficiency is increased by setting the pump to run at full speed at certain intervals to rinse out sludge.
- Temp/Speed controlled fans assures less noise, a more even drive temperature and higher efficiency.
- Load monitor function included as standard.
- Detachable multi-language control panel included as standard. Following languages are supported in the control panel:
- English, Swedish, Dutch, German, French, Spanish, Russian, Italian, Czech, Turkish and Polish.
- Operation parameters can be set in your process units, for example m3/min. and bar.
- Removable control panel with own memory means it is easy to transfer or copy settings.
- UL (UL 840) approved version available (not IP2Y).
- Marine (DNV-GL & BV) approved version available (not IP2Y, IP2x).
- Liquid cooled version available for sizes above 90 A



GENERAL SPECIFICATION

Component name	FDU69-2K6-IP
Suitable Motor Capacity	
Capacity(<i>KW</i>)	2600
Rated Output Current(A)	2600
Maximum Output Current(A)	3120
Input Voltage Range(V)	Three-phase 400~ 690V, 50/60Hz
Allowable Voltage Fluctuation	-15%~+10%
Output Voltage range(V)	Three-phase 0~480V
Mains Frequency (Hz)	45 to 65
Output Switching Frequency (<i>kHz</i>)	3
Input Power Factor (%)	0.95
Environmental conditions	
Nominal ambient temperature	0°C - 40°C (32°F- 104°F)
Atmospheric pressure	86–106 kPa (12.5 - 15.4 PSI)
Relative humidity	
according to IEC 60721-3-3	Class 3K4, 595% and no condensing
Contamination,	No electrically conductive dust allowed. Cooling air must be clean
according to IEC 60721-3-3	and free from corrosive materi-als. Chemical gases, class 3C2
	(coated boards 3C3). Solid particles, class 3S2.
Component name	VFX48-2K5-54
Vibrations	According to IEC 60068-2-6, Sinusoidal vibrations:
	10 <f<57 (0.00295="" 0.075="" ft)<="" hz,="" mm="" td=""></f<57>
	57 <f<150 (0,035="" 1g="" hz,="" oz)<="" td=""></f<150>
Altitude	0–1000 m (0 - 3280 ft) with derating 1%/100 m (328 ft) of rated current
Storago tomporaturo	
Storage temperature Storage atmospheric pressure	-20 to +60 °C (-4 to + 140 °F) 86–106 kPa (12.5 - 15.4 PSI)
Storage relative humidity according	Class 1K4, max. 95% and no condensing and no formation of ice.
to IEC60721-3-1	Class 1K4, max. 7570 and no condensing and no formation of ice.
Basic I/O Data	
Control signal inputs: Analogue (differe	ntial), 4 channels
Analogue voltage/current	0-±10 V/0-20 mA via switch
Max. input voltage	+30 V
Input impedance	20 kΩ (voltage), 250 Ω (current)
Resolution	11 bits + sign
Hardware accuracy	0.5% type + 1 ½ LSB fsd
Non-linearity	1½ LSB
Digital inputs: 8 channels	
Input voltage	High >9 VDC, Low<4 VDC
Max. input voltage	+30 VDC
Max. Input voltage	130 100

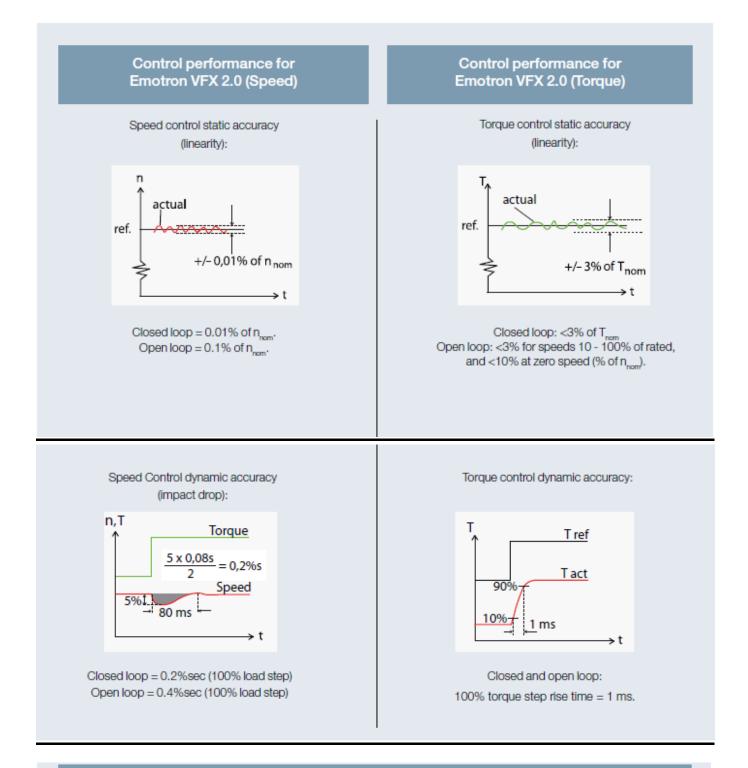
Product data sheet



Signal delay	≤8 ms	
Control signal outputs: Analogue, 2 channels		
Output voltage/current	0-10 V/0-20 mA via software setting	
Max. output voltage	+15 V @5 mA cont.	
Short-circuit current (∞)	+15 mA (voltage) +140 mA (current)	
Output impedance	10Ω (voltage)	
Resolution	10 bit	
Maximum load impedance for current	500 Ω	
Hardware accuracy	1.9% type fsd (voltage), 2.4% type fsd (current)	
Offset	3 LSB	
Non-linearity	2 LSB	
Digital outputs: 2 channels		
Output voltage	High>20 VDC @50 mA, >23 VDC open Low<1 VDC @50 mA	
Short-circuit current (∞)	100 mA max (together with +24 VDC)	
Relays, 3pcs		
Contacts	0.1 – 2 A/Umax 250 VAC or 42 VDC	
Reference voltages		
+10 VDC	+10 VDC @10 mA short-circuit current +30 mA max	
-10 VDC	-10 VDC @10 mA	
+24 VDC	+24 VDC short-circuit current +100 mA max (together with Digital Outputs)	



PERFORMANCE

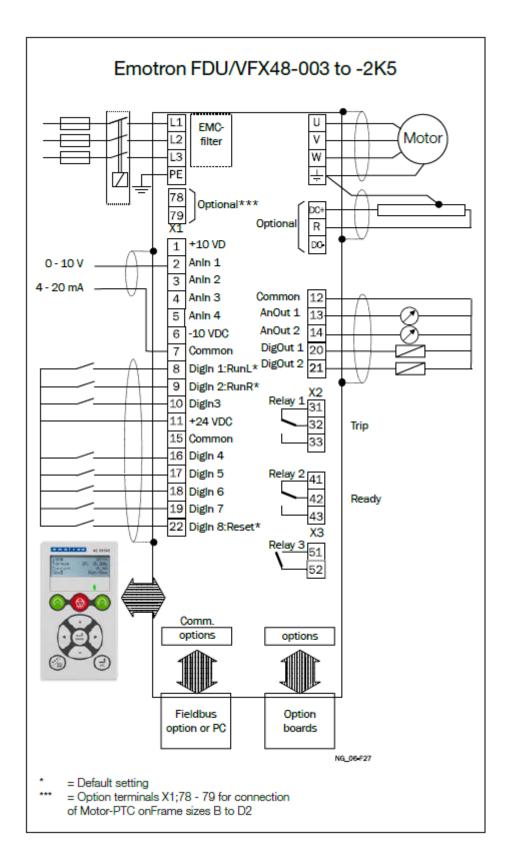


Control performance for Emotron FDU 2.0 (V/Hz)

Speed control accuracy = approximately 1% of nnom (slip frequency). Torque accuracy = approximately 5% of Tnom (20 - 100% speed).

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GENERAL WIRING DIAGRAM





X1	Name:	Function (Default):
1	+10V	+10 VDC Supply voltage
2	AnIn 1	Speed reference
3	AnIn 2	Not Used
4	AnIn 3	Not Used
5	AnIn 4	Not Used
6	-10V	-10VDC Supply voltage
7	Common	Signal ground
8	DigIn 1	RunL
9	DigIn 2	RunR
10	DigIn 3	Not Used
11	+24VDC	+24VDC Supply voltage
12	Common	Signal ground
13	AnOut 1	Min speed to max speed
14	AnOut 2	0 to max torque
15	Common	Signal ground
16	DigIn 4	Not Used
17	DigIn 5	Not Used
18	DigIn 6	Not Used
19	DigIn 7	Not Used

X1	Name:	Function (Default):
20	DigOut 1	Ready
21	DigOut 2	Brake/No trip
22	DigIn 8	Reset
X2	Name:	
31	N/C 1	Relay 1 Output= Trip.
32	COM 1	Active when the AC drive is
33	N/0 1	in a Trip condition. The N/C is opened when the relay is active (valid for all relays). The N/O is closed when the relay is active (valid for all relays).
41	N/C 2	Relay 2 Output= Ready.
42	COM 2	Active when the AC drive is
43	N/O 2	ready to start.
X3	Name:	Function (Default):
51	COM 3	Relay 3 Output= Not used.
52	N/0 3	

DRIVE DIMENSIONS (Hx Wx D): preliminary 2250x 3900x 600 (mm).



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