

## Product data sheet Emotron

### Variable speed drive VFX69-033-54/ 22KW/ 400-690V

## Main Features

- NEW - Control panel with Real time clock. Optional Bluetooth communication.
- Available as robust and certified IP54 metal construction or IP20/21 version.
- All drive sizes are delivered with a built-in Category C3 EMC-filter as standard. C3 requirements are fulfilled with 80 m motor cable (IP2Y= 25m).
- Direct torque control reacts extremely quickly and eliminates disturbances due to abrupt load changes.
- Load monitor function included as standard.
- UL (UL 840) approved version available (not IP2Y).
- Marine (DNV-GL & BV) approved version available (not IP2Y, IP2x).
- Integrated vector braking ensures quick and controlled stops, increasing productivity and safety.
- Built-in brake chopper is standard for IP2Y models and available as option for all other.
- Temp / Speed controlled fans assures less noise, a more even drive temperature and higher drive efficiency.
- Detachable multi-language control panel included as standard. Following languages are supported in the control panel:  
English, Swedish, Dutch, German, French, Spanish, Russian, Italian, Czech, Turkish and Polish.
- Operation parameters can be set in your process units, for example m/sec, tons/h or cycles/min.
- Removable control panel with own memory means it is easy to transfer or copy settings.
- Liquid cooled version available for sizes above 90 A.

## GENERAL SPECIFICATION

| Component name                                  | VFX69-033-54                         |
|---|--------------------------------------|
| Suitable Motor Capacity<br>Capacity(KW)         | 22                                   |
| Rated Output Current(A)                         | 26                                   |
| Maximum Output Current(A)                       | 53                                   |
| Input Voltage Range(V)                          | Three-phase 400~690V, 50/60Hz        |
| Allowable Voltage Fluctuation                   | -15%~+10%                            |
| Output Voltage range(V)                         | Three-phase 0~480V                   |
| Mains Frequency (Hz)                            | 45 to 65                             |
| Output Switching Frequency (kHz)                | 3                                    |
| Input Power Factor (%)                          | 0.95                                 |
| <i>Environmental conditions</i>                 |                                      |
| Nominal ambient temperature                     | 0°C - 40°C (32°F- 104°F)             |
| Atmospheric pressure                            | 86–106 kPa ( 12.5 - 15.4 PSI)        |
| Relative humidity<br>according to IEC 60721-3-3 | Class 3K4, 5...95% and no condensing |

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|   |  |
|---|--|
| Contamination, according to IEC 60721-3-3                         | No electrically conductive dust allowed. Cooling air must be clean and free from corrosive materials. Chemical gases, class 3C2 (coated boards 3C3). Solid particles, class 3S2. |
| <b>Component name</b>   | <b>VFX48-2K5-54</b>  |
| Vibrations  | According to IEC 60068-2-6, Sinusoidal vibrations:<br>10<f<57 Hz, 0.075 mm (0.00295 ft)<br>57<f<150 Hz, 1g (0,035 oz)  |
| Altitude  | 0–1000 m (0 - 3280 ft) with derating 1%/100 m (328 ft) of rated current  |
| Storage temperature   | -20 to +60 °C (-4 to + 140 °F)   |
| Storage atmospheric pressure                                      | 86–106 kPa (12.5 - 15.4 PSI)   |
| Storage relative humidity according to IEC60721-3-1               | Class 1K4, max. 95% and no condensing and no formation of ice.   |
| <i>Basic I/O Data</i>   |  |
| <i>Control signal inputs: Analogue (differential), 4 channels</i> |  |
| Analogue voltage/current  | 0-±10 V/0-20 mA via switch   |
| Max. input voltage  | +30 V  |
| Input impedance   | 20 kΩ (voltage), 250 Ω (current)   |
| Resolution  | 11 bits + sign   |
| Hardware accuracy   | 0.5% type + 1 ½ LSB fsd  |
| Non-linearity   | 1½ LSB   |
| <i>Digital inputs: 8 channels</i>                                 |  |
| Input voltage   | High >9 VDC, Low <4 VDC  |
| Max. input voltage  | +30 VDC  |
| Input impedance   | <3.3 VDC: 4.7 kΩ, ≥3.3 VDC: 3.6 kΩ   |
| Signal delay  | ≤8 ms  |
| <i>Control signal outputs: Analogue, 2 channels</i>               |  |
| Output voltage/current  | 0-10 V/0-20 mA via software setting  |
| Max. output voltage   | +15 V @5 mA cont.  |
| Short-circuit current (∞)   | +15 mA (voltage) +140 mA (current)   |
| Output impedance  | 10 Ω (voltage)   |
| Resolution  | 10 bit   |
| Maximum load impedance for current                                | 500 Ω  |
| Hardware accuracy   | 1.9% type fsd (voltage), 2.4% type fsd (current)   |
| Offset  | 3 LSB  |
| Non-linearity   | 2 LSB  |
| <i>Digital outputs: 2 channels</i>                                |  |
| Output voltage  | High >20 VDC @50 mA, >23 VDC open<br>Low <1 VDC @50 mA   |
| Short-circuit current (∞)   | 100 mA max (together with +24 VDC)   |
| <i>Relays, 3pcs</i>   |  |
| Contacts  | 0.1 – 2 A/Umax 250 VAC or 42 VDC   |
| <i>Reference voltages</i>   |  |
| +10 VDC   | +10 VDC @10 mA short-circuit current +30 mA max  |
| -10 VDC   | -10 VDC @10 mA   |

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+24 VDC

+24 VDC short-circuit current +100 mA max (together with Digital Outputs)

## PERFORMANCE

### Control performance for Emotron VFX 2.0 (Speed)

Speed control static accuracy  
(linearity):



Closed loop = 0.01% of  $n_{nom}$   
Open loop = 0.1% of  $n_{nom}$

### Control performance for Emotron VFX 2.0 (Torque)

Torque control static accuracy  
(linearity):



Closed loop: <3% of  $T_{nom}$   
Open loop: <3% for speeds 10 - 100% of rated, and <10% at zero speed (% of  $n_{nom}$ ).

Speed Control dynamic accuracy  
(impact drop):



Closed loop = 0.2%sec (100% load step)  
Open loop = 0.4%sec (100% load step)

Torque control dynamic accuracy:



Closed and open loop:  
100% torque step rise time = 1 ms.

## Control performance for Emotron FDU 2.0 (V/Hz)

Speed control accuracy =  
approximately 1% of  $n_{nom}$   
(slip frequency).

Torque accuracy =  
approximately 5% of  $T_{nom}$   
(20 - 100% speed).

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## GENERAL WIRING DIAGRAM



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| X1 | Name:   | Function (Default):    |
|----|---------|------------------------|
| 1  | +10V    | +10 VDC Supply voltage |
| 2  | AnIn 1  | Speed reference        |
| 3  | AnIn 2  | Not Used               |
| 4  | AnIn 3  | Not Used               |
| 5  | AnIn 4  | Not Used               |
| 6  | -10V    | -10VDC Supply voltage  |
| 7  | Common  | Signal ground          |
| 8  | DigIn 1 | RunL                   |
| 9  | DigIn 2 | RunR                   |
| 10 | DigIn 3 | Not Used               |
| 11 | +24VDC  | +24VDC Supply voltage  |
| 12 | Common  | Signal ground          |
| 13 | AnOut 1 | Min speed to max speed |
| 14 | AnOut 2 | 0 to max torque        |
| 15 | Common  | Signal ground          |
| 16 | DigIn 4 | Not Used               |
| 17 | DigIn 5 | Not Used               |
| 18 | DigIn 6 | Not Used               |
| 19 | DigIn 7 | Not Used               |

| X1 | Name:    | Function (Default):  |
|----|----------|--|
| 20 | DigOut 1 | Ready  |
| 21 | DigOut 2 | Brake/No trip  |
| 22 | DigIn 8  | Reset  |
| X2 | Name:    | Function (Default):  |
| 31 | N/C 1    | Relay 1 Output= Trip.<br>Active when the AC drive is in a Trip condition. The N/C is opened when the relay is active (valid for all relays).<br>The N/O is closed when the relay is active (valid for all relays). |
| 32 | COM 1    |  |
| 33 | N/O 1    |  |
| 41 | N/C 2    | Relay 2 Output= Ready.<br>Active when the AC drive is ready to start.  |
| 42 | COM 2    |  |
| 43 | N/O 2    |  |
| X3 | Name:    | Function (Default):  |
| 51 | COM 3    | Relay 3 Output= Not used.  |
| 52 | N/O 3    |  |

## DRIVE DIMENSIONS

(Hx Wx D): preliminary 590x 220x 295 (mm).



### Head Office, Sydney

TECO Australia Pty Ltd  
335-337 Woodpark Road,  
Smithfield NSW 2164  
Tel: 02 9765 8118  
Fax: 02 9604 9330



### Melbourne

TECO Australia Pty Ltd  
16 Longstaff Road,  
Bayswater VIC 3153  
Tel: 03 9720 4411  
Fax: 03 9720 5355



### Brisbane

TECO Australia Pty Ltd  
50 Murdoch Circuit,  
Acacia Ridge QLD 4110  
Tel: 07 3373 9600  
Fax: 07 3373 9699



### Perth

TECO Australia Pty Ltd  
18 Hazelhurst Street,  
Kewdale WA 6105  
Tel: 08 9479 4879  
Fax: 08 9478 3876



### New Zealand

TECO New Zealand Ltd  
Unit 3, 477 Great South Road,  
Penrose, Auckland  
Tel: 64 9-526 8480  
Fax: 64 9-526 8484  
sales@teco.co.nz