

# Main Features

- NEW Control panel with Real time clock. Optional Bluetooth communication.
- Available as robust and certified IP54 metal construction or IP20/21 version.
- All drive sizes are delivered with a built-in Category C3 EMC-filter as standard. C3 requirements are fulfilled with 80 m motor cable (IP2Y= 25m).
- Direct torque control reacts extremely quickly and eliminates disturbances due to abrupt load changes.
- Load monitor function included as standard.
- UL (UL 840) approved version available (not IP2Y).
- Marine (DNV-GL & BV) approved version available (not IP2Y, IP2x).
- Integrated vector braking ensures quick and controlled stops, increasing productivity and safety.
- Built-in brake chopper is standard for IP2Y models and available as option for all other.
- Temp / Speed controlled fans assures less noise, a more even drive temperature and higher drive efficiency.
- Detachable multi-language control panel included as standard. Following languages are supported in the control panel:
- English, Swedish, Dutch, German, French, Spanish, Russian, Italian, Czech, Turkish and Polish.
- Operation parameters can be set in your process units, for example m/sec, tons/h or cycles/min.
- Removable control panel with own memory means it is easy to transfer or copy settings.
- Liquid cooled version available for sizes above 90 A.

| Component name                                  | VFX48-210-54                      |
|---|-----------------------------------|
| Suitable Motor Capacity<br>Capacity <i>(KW)</i> | 90                                |
| Rated Output Current(A)                         | 168                               |
| Maximum Output Current(A)                       | 252                               |
| Input Voltage Range(V)                          | Three-phase 230~ 480V, 50/60Hz    |
| Allowable Voltage Fluctuation                   | -15%~ +10%                        |
| Output Voltage range(V)                         | Three-phase 0~480V                |
| Mains Frequency (Hz)                            | 45 to 65                          |
| Output Switching Frequency (kHz)                | 3                                 |
| Input Power Factor (%)                          | 0.95                              |
| Environmental conditions                        |                                   |
| Nominal ambient temperature                     | 0°C - 40°C (32°F- 104°F)          |
| Atmospheric pressure                            | 86–106 kPa ( 12.5 - 15.4 PSI)     |
| Relative humidity<br>according to IEC 60721-3-3 | Class 3K4, 595% and no condensing |

### GENERAL SPECIFICATION



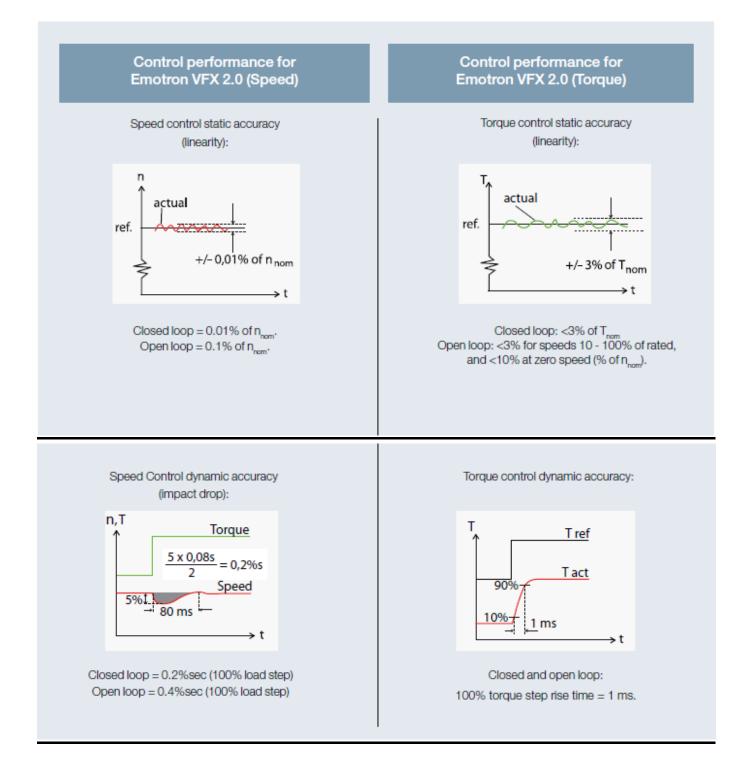
| Contamination,<br>according to IEC 60721-3-3   | No electrically conductive dust allowed. Cooling air must be clean<br>and free from corrosive materi-als. Chemical gases, class 3C2<br>(coated boards 3C3). Solid particles, class 3S2.<br>VFX48-2K5-54   |  |  |
|--|---|--|--|
| Component name<br>Vibrations   | According to IEC 60068-2-6, Sinusoidal vibrations:<br>10 <f<57 (0.00295="" 0.075="" ft)<br="" hz,="" mm="">57<f<150 (0,035="" 1g="" hz,="" oz)<="" td=""></f<150></f<57>  |  |  |
| Altitude   | 0–1000 m (0 - 3280 ft) with derating 1%/100 m (328 ft) of rated current   |  |  |
| Storage temperature  | -20 to +60 °C (-4 to + 140 °F)  |  |  |
| Storage atmospheric pressure   | 86–106 kPa (12.5 - 15.4 PSI)  |  |  |
| Storage relative humidity according to IEC60721-3-1  | Class 1K4, max. 95% and no condensing and no formation of ice.  |  |  |
| Basic I/O Data<br>Control signal inputs: Analogue (differential), 4 channels   |   |  |  |
| Analogue voltage/current   | 0-±10 V/0-20 mA via switch  |  |  |
| Max. input voltage   | +30 V   |  |  |
| Input impedance<br>Resolution  | 20 kΩ (voltage), 250 Ω (current)  |  |  |
| Hardware accuracy  | 11 bits + sign<br>0.5% type + 1 ½ LSB fsd   |  |  |
| Non-linearity  | 1½ LSB  |  |  |
| Digital inputs: 8 channels   | 172 101   |  |  |
| Input voltage  | High >9 VDC, Low<4 VDC  |  |  |
| Max. input voltage   | +30 VDC   |  |  |
| Input impedance  | <3.3 VDC: 4.7 kΩ , ≥3.3 VDC: 3.6 kΩ   |  |  |
| Signal delay   | ≤8 ms   |  |  |
|  | Control signal outputs: Analogue, 2 channels  |  |  |
|  | nnels   |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current   | 0-10 V/0-20 mA via software setting   |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current<br>Max. output voltage  | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.  |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current<br>Max. output voltage<br>Short-circuit current (∞)   | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)  |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current<br>Max. output voltage<br>Short-circuit current (∞)<br>Output impedance   | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)<br>10 $\Omega$ (voltage)   |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current<br>Max. output voltage<br>Short-circuit current (∞)<br>Output impedance<br>Resolution   | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)<br>10 Ω (voltage)<br>10 bit  |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current<br>Max. output voltage<br>Short-circuit current (∞)<br>Output impedance<br>Resolution<br>Maximum load impedance for current   | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)<br>10 Ω (voltage)<br>10 bit<br>500 Ω   |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current<br>Max. output voltage<br>Short-circuit current (∞)<br>Output impedance<br>Resolution<br>Maximum load impedance for current<br>Hardware accuracy  | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)<br>10 Ω (voltage)<br>10 bit<br>500 Ω<br>1.9% type fsd (voltage), 2.4% type fsd (current)   |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current<br>Max. output voltage<br>Short-circuit current (∞)<br>Output impedance<br>Resolution<br>Maximum load impedance for current<br>Hardware accuracy<br>Offset  | $\begin{array}{l} 0-10 \text{ V/0-20 mA via software setting} \\ +15 \text{ V @5 mA cont.} \\ +15 \text{ mA (voltage) +140 mA (current)} \\ 10 \Omega (voltage) \\ 10 \text{ bit} \\ 500 \Omega \\ 1.9\% \text{ type fsd (voltage), 2.4\% type fsd (current)} \\ 3 \text{ LSB} \end{array}$   |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current<br>Max. output voltage<br>Short-circuit current (∞)<br>Output impedance<br>Resolution<br>Maximum load impedance for current<br>Hardware accuracy<br>Offset<br>Non-linearity   | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)<br>10 Ω (voltage)<br>10 bit<br>500 Ω<br>1.9% type fsd (voltage), 2.4% type fsd (current)   |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current<br>Max. output voltage<br>Short-circuit current (∞)<br>Output impedance<br>Resolution<br>Maximum load impedance for current<br>Hardware accuracy<br>Offset  | $\begin{array}{l} 0-10 \text{ V/0-20 mA via software setting} \\ +15 \text{ V @5 mA cont.} \\ +15 \text{ mA (voltage) +140 mA (current)} \\ 10 \Omega (voltage) \\ 10 \text{ bit} \\ 500 \Omega \\ 1.9\% \text{ type fsd (voltage), 2.4\% type fsd (current)} \\ 3 \text{ LSB} \end{array}$   |  |  |
| Control signal outputs: Analogue, 2 char<br>Output voltage/current<br>Max. output voltage<br>Short-circuit current (∞)<br>Output impedance<br>Resolution<br>Maximum load impedance for current<br>Hardware accuracy<br>Offset<br>Non-linearity<br>Digital outputs: 2 channels  | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)<br>10 Ω (voltage)<br>10 bit<br>500 Ω<br>1.9% type fsd (voltage), 2.4% type fsd (current)<br>3 LSB<br>2 LSB<br>High>20 VDC @50 mA, >23 VDC open   |  |  |
| Control signal outputs: Analogue, 2 charOutput voltage/currentMax. output voltageShort-circuit current ( $\infty$ )Output impedanceResolutionMaximum load impedance for currentHardware accuracyOffsetNon-linearityDigital outputs: 2 channelsOutput voltage   | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)<br>10 Ω (voltage)<br>10 bit<br>500 Ω<br>1.9% type fsd (voltage), 2.4% type fsd (current)<br>3 LSB<br>2 LSB<br>High>20 VDC @50 mA, >23 VDC open<br>Low<1 VDC @50 mA   |  |  |
| Control signal outputs: Analogue, 2 charOutput voltage/currentMax. output voltageShort-circuit current ( $\infty$ )Output impedanceResolutionMaximum load impedance for currentHardware accuracyOffsetNon-linearityDigital outputs: 2 channelsOutput voltageShort-circuit current ( $\infty$ )Relays, 3pcsContacts                   | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)<br>10 Ω (voltage)<br>10 bit<br>500 Ω<br>1.9% type fsd (voltage), 2.4% type fsd (current)<br>3 LSB<br>2 LSB<br>High>20 VDC @50 mA, >23 VDC open<br>Low<1 VDC @50 mA   |  |  |
| Control signal outputs: Analogue, 2 charOutput voltage/currentMax. output voltageShort-circuit current ( $\infty$ )Output impedanceResolutionMaximum load impedance for currentHardware accuracyOffsetNon-linearityDigital outputs: 2 channelsOutput voltageShort-circuit current ( $\infty$ )Relays, 3pcsContactsReference voltages | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)<br>10 Ω (voltage)<br>10 bit<br>500 Ω<br>1.9% type fsd (voltage), 2.4% type fsd (current)<br>3 LSB<br>2 LSB<br>High>20 VDC @50 mA, >23 VDC open<br>Low<1 VDC @50 mA<br>100 mA max (together with +24 VDC)<br>0.1 – 2 A/Umax 250 VAC or 42 VDC |  |  |
| Control signal outputs: Analogue, 2 charOutput voltage/currentMax. output voltageShort-circuit current ( $\infty$ )Output impedanceResolutionMaximum load impedance for currentHardware accuracyOffsetNon-linearityDigital outputs: 2 channelsOutput voltageShort-circuit current ( $\infty$ )Relays, 3pcsContacts                   | 0-10 V/0-20 mA via software setting<br>+15 V @5 mA cont.<br>+15 mA (voltage) +140 mA (current)<br>10 Ω (voltage)<br>10 bit<br>500 Ω<br>1.9% type fsd (voltage), 2.4% type fsd (current)<br>3 LSB<br>2 LSB<br>High>20 VDC @50 mA, >23 VDC open<br>Low<1 VDC @50 mA   |  |  |

## **Product data sheet**



| +24 VDC | +24 VDC short-circuit current +100 mA max (together with |
|---------|--|
|         | Digital Outputs)   |

#### PERFORMANCE



### **Product data sheet**

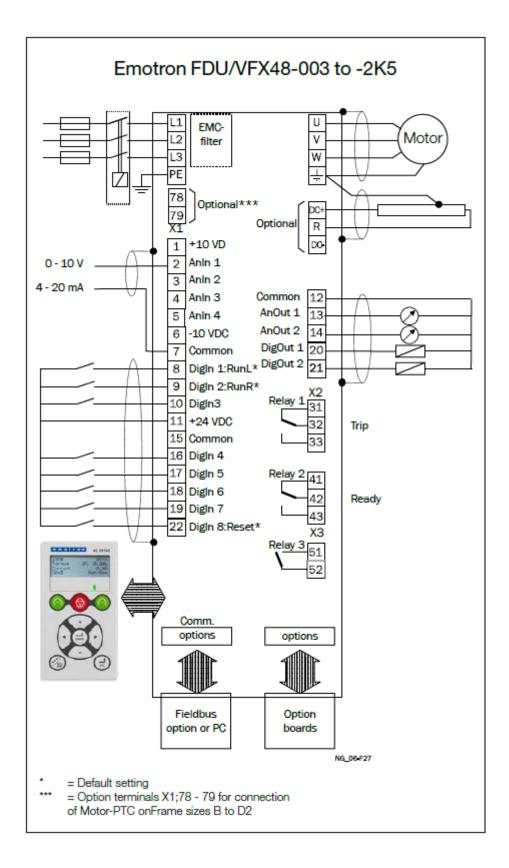


#### Control performance for Emotron FDU 2.0 (V/Hz)

Speed control accuracy = approximately 1% of nnom (slip frequency). Torque accuracy = approximately 5% of Tnom (20 - 100% speed).

# TEC

## GENERAL WIRING DIAGRAM





| X1 | Name:   | Function (Default):    |
|----|---------|------------------------|
| 1  | +10V    | +10 VDC Supply voltage |
| 2  | AnIn 1  | Speed reference        |
| 3  | AnIn 2  | Not Used               |
| 4  | AnIn 3  | Not Used               |
| 5  | AnIn 4  | Not Used               |
| 6  | -10V    | -10VDC Supply voltage  |
| 7  | Common  | Signal ground          |
| 8  | DigIn 1 | RunL                   |
| 9  | DigIn 2 | RunR                   |
| 10 | DigIn 3 | Not Used               |
| 11 | +24VDC  | +24VDC Supply voltage  |
| 12 | Common  | Signal ground          |
| 13 | AnOut 1 | Min speed to max speed |
| 14 | AnOut 2 | 0 to max torque        |
| 15 | Common  | Signal ground          |
| 16 | DigIn 4 | Not Used               |
| 17 | DigIn 5 | Not Used               |
| 18 | DigIn 6 | Not Used               |
| 19 | DigIn 7 | Not Used               |

| X1 | Name:    | Function (Default):   |
|----|----------|---|
| 20 | DigOut 1 | Ready   |
| 21 | DigOut 2 | Brake/No trip   |
| 22 | DigIn 8  | Reset   |
| X2 | Name:    |   |
| 31 | N/C 1    | Relay 1 Output= Trip.   |
| 32 | COM 1    | Active when the AC drive is   |
| 33 | N/0 1    | in a Trip condition. The N/C<br>is opened when the relay is<br>active (valid for all relays).<br>The N/O is closed when the<br>relay is active (valid for all<br>relays). |
| 41 | N/C 2    | Relay 2 Output= Ready.  |
| 42 | COM 2    | Active when the AC drive is   |
| 43 | N/O 2    | ready to start.   |
| X3 | Name:    | Function (Default):   |
| 51 | COM 3    | Relay 3 Output= Not used.   |
| 52 | N/0 3    |   |

#### **DRIVE DIMENSIONS** (Hx Wx D): preliminary 950x 345x 314 (mm).

Fax: 02 9604 9330



Fax: 07 3373 9699

Fax: 08 9478 3876

Fax: 03 9720 5355

Unit 3, 477 Great South Road, Penrose, Auckland Tel: 64 9-526 8480 Fax: 64 9-526 8484 sales@teco.co.nz