

Main Features

- NEW Control panel with Real time clock. Optional Bluetooth communication.
- Available as robust and certified IP54 metal construction or IP20/21 version.
- All drive sizes are delivered with a built-in Category C3 EMC-filter as standard. C3 requirements are fulfilled with 80 m motor cable (IP2Y= 25m).
- Direct torque control reacts extremely quickly and eliminates disturbances due to abrupt load changes.
- Load monitor function included as standard.
- UL (UL 840) approved version available (not IP2Y).
- Marine (DNV-GL & BV) approved version available (not IP2Y, IP2x).
- Integrated vector braking ensures quick and controlled stops, increasing productivity and safety.
- Built-in brake chopper is standard for IP2Y models and available as option for all other.
- Temp / Speed controlled fans assures less noise, a more even drive temperature and higher drive efficiency.
- Detachable multi-language control panel included as standard. Following languages are supported in the control panel:
- English, Swedish, Dutch, German, French, Spanish, Russian, Italian, Czech, Turkish and Polish.
- Operation parameters can be set in your process units, for example m/sec, tons/h or cycles/min.
- Removable control panel with own memory means it is easy to transfer or copy settings.
- Liquid cooled version available for sizes above 90 A.

| Component name | VFX69-1K4-IP |
|---|-----------------------------------|
| Suitable Motor Capacity Capacity <i>(KW)</i> | 1120 |
| Rated Output Current(A) | 1120 |
| Maximum Output Current(A) | 1680 |
| Input Voltage Range(V) | Three-phase 400~ 690V, 50/60Hz |
| Allowable Voltage Fluctuation | -15%~ +10% |
| Output Voltage range(V) | Three-phase 0~480V |
| Mains Frequency (Hz) | 45 to 65 |
| Output Switching Frequency (kHz) | 3 |
| Input Power Factor (%) | 0.95 |
| Environmental conditions | |
| Nominal ambient temperature | 0°C - 40°C (32°F- 104°F) |
| Atmospheric pressure | 86–106 kPa (12.5 - 15.4 PSI) |
| Relative humidity according to IEC 60721-3-3 | Class 3K4, 595% and no condensing |

GENERAL SPECIFICATION



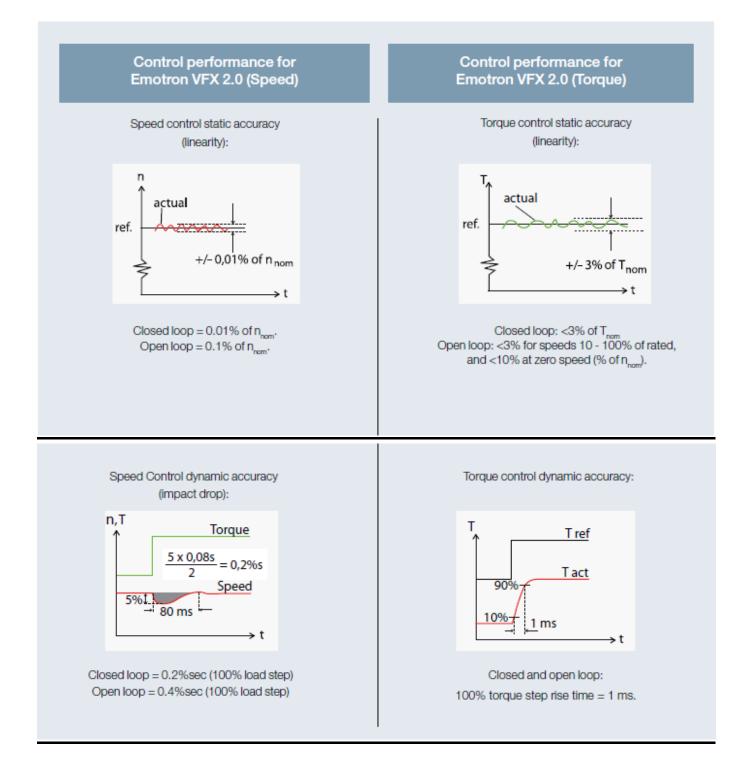
| Contamination, according to IEC 60721-3-3 | No electrically conductive dust allowed. Cooling air must be clean and free from corrosive materi-als. Chemical gases, class 3C2 (coated boards 3C3). Solid particles, class 3S2. VFX48-2K5-54 | | |
|--|---|--|--|
| Component name Vibrations | According to IEC 60068-2-6, Sinusoidal vibrations: 10 <f<57 (0.00295="" 0.075="" ft)<br="" hz,="" mm="">57<f<150 (0,035="" 1g="" hz,="" oz)<="" td=""></f<150></f<57> | | |
| Altitude | 0–1000 m (0 - 3280 ft) with derating 1%/100 m (328 ft) of rated current | | |
| Storage temperature | -20 to +60 °C (-4 to + 140 °F) | | |
| Storage atmospheric pressure | 86–106 kPa (12.5 - 15.4 PSI) | | |
| Storage relative humidity according to IEC60721-3-1 | Class 1K4, max. 95% and no condensing and no formation of ice. | | |
| Basic I/O Data Control signal inputs: Analogue (differential), 4 channels | | | |
| Analogue voltage/current | 0-±10 V/0-20 mA via switch | | |
| Max. input voltage | +30 V | | |
| Input impedance Resolution | 20 kΩ (voltage), 250 Ω (current) | | |
| Hardware accuracy | 11 bits + sign 0.5% type + 1 ½ LSB fsd | | |
| Non-linearity | 1½ LSB | | |
| Digital inputs: 8 channels | 172 101 | | |
| Input voltage | High >9 VDC, Low<4 VDC | | |
| Max. input voltage | +30 VDC | | |
| Input impedance | <3.3 VDC: 4.7 kΩ , ≥3.3 VDC: 3.6 kΩ | | |
| Signal delay | ≤8 ms | | |
| | Control signal outputs: Analogue, 2 channels | | |
| | nnels | | |
| Control signal outputs: Analogue, 2 char Output voltage/current | 0-10 V/0-20 mA via software setting | | |
| Control signal outputs: Analogue, 2 char Output voltage/current Max. output voltage | 0-10 V/0-20 mA via software setting +15 V @5 mA cont. | | |
| Control signal outputs: Analogue, 2 char Output voltage/current Max. output voltage Short-circuit current (∞) | 0-10 V/0-20 mA via software setting +15 V @5 mA cont. +15 mA (voltage) +140 mA (current) | | |
| Control signal outputs: Analogue, 2 char Output voltage/current Max. output voltage Short-circuit current (∞) Output impedance | 0-10 V/0-20 mA via software setting +15 V @5 mA cont. +15 mA (voltage) +140 mA (current) 10 Ω (voltage) | | |
| Control signal outputs: Analogue, 2 char Output voltage/current Max. output voltage Short-circuit current (∞) Output impedance Resolution | 0-10 V/0-20 mA via software setting +15 V @5 mA cont. +15 mA (voltage) +140 mA (current) 10 Ω (voltage) 10 bit | | |
| Control signal outputs: Analogue, 2 char Output voltage/current Max. output voltage Short-circuit current (∞) Output impedance Resolution Maximum load impedance for current | 0-10 V/0-20 mA via software setting +15 V @5 mA cont. +15 mA (voltage) +140 mA (current) 10 Ω (voltage) 10 bit 500 Ω | | |
| Control signal outputs: Analogue, 2 char Output voltage/current Max. output voltage Short-circuit current (∞) Output impedance Resolution Maximum load impedance for current Hardware accuracy | 0-10 V/0-20 mA via software setting +15 V @5 mA cont. +15 mA (voltage) +140 mA (current) 10 Ω (voltage) 10 bit 500 Ω 1.9% type fsd (voltage), 2.4% type fsd (current) | | |
| Control signal outputs: Analogue, 2 char Output voltage/current Max. output voltage Short-circuit current (∞) Output impedance Resolution Maximum load impedance for current Hardware accuracy Offset | $\begin{array}{l} 0-10 \text{ V/0-20 mA via software setting} \\ +15 \text{ V @5 mA cont.} \\ +15 \text{ mA (voltage) +140 mA (current)} \\ 10 \Omega (voltage) \\ 10 \text{ bit} \\ 500 \Omega \\ 1.9\% \text{ type fsd (voltage), 2.4\% type fsd (current)} \\ 3 \text{ LSB} \end{array}$ | | |
| Control signal outputs: Analogue, 2 char Output voltage/current Max. output voltage Short-circuit current (∞) Output impedance Resolution Maximum load impedance for current Hardware accuracy Offset Non-linearity | 0-10 V/0-20 mA via software setting +15 V @5 mA cont. +15 mA (voltage) +140 mA (current) 10 Ω (voltage) 10 bit 500 Ω 1.9% type fsd (voltage), 2.4% type fsd (current) | | |
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| Control signal outputs: Analogue, 2 charOutput voltage/currentMax. output voltageShort-circuit current (∞)Output impedanceResolutionMaximum load impedance for currentHardware accuracyOffsetNon-linearityDigital outputs: 2 channelsOutput voltage | 0-10 V/0-20 mA via software setting +15 V @5 mA cont. +15 mA (voltage) +140 mA (current) 10 Ω (voltage) 10 bit 500 Ω 1.9% type fsd (voltage), 2.4% type fsd (current) 3 LSB 2 LSB High>20 VDC @50 mA, >23 VDC open Low<1 VDC @50 mA | | |
| Control signal outputs: Analogue, 2 charOutput voltage/currentMax. output voltageShort-circuit current (∞)Output impedanceResolutionMaximum load impedance for currentHardware accuracyOffsetNon-linearityDigital outputs: 2 channelsOutput voltageShort-circuit current (∞)Relays, 3pcsContacts | 0-10 V/0-20 mA via software setting +15 V @5 mA cont. +15 mA (voltage) +140 mA (current) 10 Ω (voltage) 10 bit 500 Ω 1.9% type fsd (voltage), 2.4% type fsd (current) 3 LSB 2 LSB High>20 VDC @50 mA, >23 VDC open Low<1 VDC @50 mA | | |
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| Control signal outputs: Analogue, 2 charOutput voltage/currentMax. output voltageShort-circuit current (∞)Output impedanceResolutionMaximum load impedance for currentHardware accuracyOffsetNon-linearityDigital outputs: 2 channelsOutput voltageShort-circuit current (∞)Relays, 3pcsContacts | 0-10 V/0-20 mA via software setting +15 V @5 mA cont. +15 mA (voltage) +140 mA (current) 10 Ω (voltage) 10 bit 500 Ω 1.9% type fsd (voltage), 2.4% type fsd (current) 3 LSB 2 LSB High>20 VDC @50 mA, >23 VDC open Low<1 VDC @50 mA | | |

Product data sheet



| +24 VDC | +24 VDC short-circuit current +100 mA max (together with |
|---------|--|
| | Digital Outputs) |

PERFORMANCE



Product data sheet

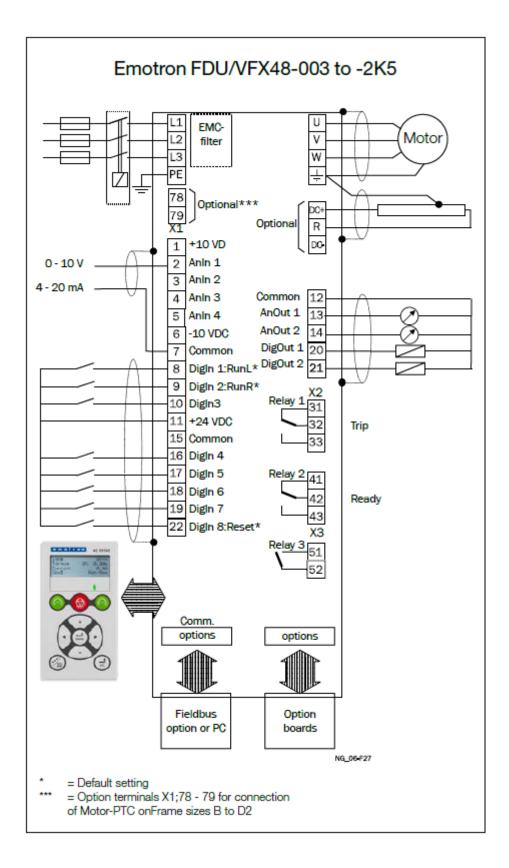


Control performance for Emotron FDU 2.0 (V/Hz)

Speed control accuracy = approximately 1% of nnom (slip frequency). Torque accuracy = approximately 5% of Tnom (20 - 100% speed).

TEC

GENERAL WIRING DIAGRAM





| X1 | Name: | Function (Default): |
|----|---------|------------------------|
| 1 | +10V | +10 VDC Supply voltage |
| 2 | AnIn 1 | Speed reference |
| 3 | AnIn 2 | Not Used |
| 4 | AnIn 3 | Not Used |
| 5 | AnIn 4 | Not Used |
| 6 | -10V | -10VDC Supply voltage |
| 7 | Common | Signal ground |
| 8 | DigIn 1 | RunL |
| 9 | DigIn 2 | RunR |
| 10 | DigIn 3 | Not Used |
| 11 | +24VDC | +24VDC Supply voltage |
| 12 | Common | Signal ground |
| 13 | AnOut 1 | Min speed to max speed |
| 14 | AnOut 2 | 0 to max torque |
| 15 | Common | Signal ground |
| 16 | DigIn 4 | Not Used |
| 17 | DigIn 5 | Not Used |
| 18 | DigIn 6 | Not Used |
| 19 | DigIn 7 | Not Used |

| X1 | Name: | Function (Default): |
|----|----------|---|
| 20 | DigOut 1 | Ready |
| 21 | DigOut 2 | Brake/No trip |
| 22 | DigIn 8 | Reset |
| X2 | Name: | |
| 31 | N/C 1 | Relay 1 Output= Trip. |
| 32 | COM 1 | Active when the AC drive is |
| 33 | N/0 1 | in a Trip condition. The N/C is opened when the relay is active (valid for all relays). The N/O is closed when the relay is active (valid for all relays). |
| 41 | N/C 2 | Relay 2 Output= Ready. |
| 42 | COM 2 | Active when the AC drive is |
| 43 | N/O 2 | ready to start. |
| X3 | Name: | Function (Default): |
| 51 | COM 3 | Relay 3 Output= Not used. |
| 52 | N/0 3 | |

DRIVE DIMENSIONS (Hx Wx D): preliminary 2250x 2100x 600 (mm).

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